

INSTRUMENTAL VARIABLE ESTIMATION OF NONPARAMETRIC MODELS

BY WHITNEY K. NEWAY AND JAMES L. POWELL

Presented by Jiyeon Seo and Yonghyeon Yang

22nd, Feb.

- Model

- Structural Form

- : $y = g(x, z_1, \varepsilon)$, $E[\varepsilon|z] = 0$, $z = (z_1, z_2)$

- Objective : To identify $g(\cdot)$.

- If g is invertible, $\varepsilon = \rho(y, x, z_1)$

- Additive Model

$$y = g_0(x, z_1) + \varepsilon , \quad E[\varepsilon|z] = 0, \quad z = (z_1, z_2)$$

$$\pi(z) = E[y|z] = E[g_0(x, z_1) | z]$$

$$= \int g_0(x, z_1) dF(x|z)$$

- : Nonparametric version of Reduced Form for y

- Identification

: π and F are obtained from data

: Identification Problem

= Problem of obtaining the unique solution of g from the reduced form

- **Proposition 2.1**

: Define $\delta(x, z_1) \equiv \tilde{g}(x, z_1) - g_0(x, z_1)$.

: g_0 is identified if only if

. $\forall \delta(x, z_1)$ with finite expectation, $E[\delta(x, z_1) | z] = 0$ implies $\delta(x, z_1) = 0$.

- completeness of conditional distribution of x given z

- (cf. complete sufficient statistic)

- special case?

- ESTIMATION: NP2SLS

: $\hat{\pi}(z) = \int g(x, z_1) d\hat{F}(x|z)$

: i.i.d. data (y_i, x_i, z_i)

- Issue : "Ill-posed inversion" problem

- How to overcome?

CASE1 : $w = (x, z_1)$ is bounded.

$$g_0(w) \simeq \sum \gamma_j p_j(w)$$

$$\pi(z) \simeq \int \sum \gamma_j p_j(w) dF(x|z) = \sum \gamma_j E[p_j(w)|z]$$

- Example

$$g_0(w) = w\gamma$$

$$y = w\gamma + \varepsilon$$

$$w = z\alpha + \eta \quad \text{where } z \perp \eta, z \perp \varepsilon$$

$$P_z y = P_z w \gamma + P_z \varepsilon, \quad E[P_z \varepsilon | z] = 0$$

$$\gamma = \left((P_z w)' P_z w \right)^{-1} (P_z w)' P_z y \quad : 2SLS$$

CASE2 : w is unbounded.

$$g_0(w) = a(w)' \beta + g_1(w)$$

$$- g_0(w) = a(w)' \beta + \sum_j \gamma_j p_j(\hat{w}) \quad \text{where} \quad \hat{w} = \hat{\Sigma}_1^{-1/2} (w - \hat{\mu}_1)$$

$$- \pi(z) = \int g_0(w) dF(x|z) = E[a(w)|z]' \beta + \sum_j \gamma_j E[p_j(\hat{w})|z]$$

$$- \text{Let } y = \pi(z) + \varepsilon$$

$$\min \frac{1}{n} \sum_i \hat{\varepsilon}^2 = \frac{1}{n} \sum_i \left\{ y_i - \hat{E}[a|z_i]' \beta - \sum_j \gamma_j \hat{E}[p_j(\hat{w})|z_i] \right\}^2$$

$$\text{s.t.} \quad \beta' \beta \leq B_\beta, \quad \|g_1\| \leq B_1$$

$$\begin{pmatrix} \hat{\beta} \\ \hat{\gamma} \end{pmatrix} = \left(\hat{R}' \hat{R} + \begin{pmatrix} \hat{\zeta}_\beta I & 0 \\ 0 & \hat{\zeta}_g \Lambda_J \end{pmatrix} \right)^{-1} \hat{R}' Y$$

$$\text{where } \hat{R} = \begin{pmatrix} \hat{E}[a|z_1]' & \hat{E}[p_1|z_1] & \cdots & \hat{E}[p_J|z_1] \\ \vdots & \vdots & \ddots & \vdots \\ \hat{E}[a|z_n]' & \hat{E}[p_1|z_n] & \cdots & \hat{E}[p_J|z_n] \end{pmatrix}$$

- Extension : General CMR

$$\hat{\rho}(z_i; \theta) = \left[\sum_l \rho(y_l, x_l; \theta) q_l^{K'} / n \right] \hat{M}^{-1} q^K(z_i)$$

$$\begin{aligned} \hat{\varepsilon} &= \hat{\rho} \\ &= Q^K (Q^{K'} Q^K)^{-1} Q^{K'} \rho \quad \text{where } Q^K = (q_1^K, \dots, q_n^K)' \end{aligned}$$

$$\hat{\theta} = \arg \min_{\theta \in \Theta_J} \sum_i \hat{\rho}(z_i; \theta)' \hat{A} \hat{\rho}(z_i; \theta) \quad \text{subject to constraints}$$

- **CONSISTENCY : General CMR**

Assumption 1 : $\theta_0 \in \Theta$ is the only $\theta \in \Theta$ satisfying $E [\rho (y, x, \theta) |z] = 0$

Assumption 2 : For any $b (z)$ with $E [b (z)^2] < \infty$, there is π_K with $E \left[\left\{ b (z) - q^K (z)' \pi_K \right\}^2 \right] \rightarrow 0$, $K \rightarrow \infty$, and $K/n \rightarrow 0$. Also, $\hat{A} \xrightarrow{p} A$, and A is positive definite and constant.

Assumption 3 : $E \left[\|\rho (y, x, \theta_0)\|^2 |z \right]$ is bounded and there exists $M (y, x)$, $\nu > 0$ such that for all $\tilde{\theta}$, $\theta \in \Theta$, $\|\rho (y, x, \tilde{\theta}) - \rho (y, x, \theta)\| \leq M (y, x) \|\tilde{\theta} - \theta\|^\nu$ and $E \left[M (y, x)^2 |z \right]$ is bounded.

Assumption 4 : $\theta_0 \in \Theta$, and Θ is compact for the norm $\|\theta\|$.

Assumption 5 :

For any $\theta \in \Theta$ there exists $\theta_J \in \Theta_J$ such that $\lim_{J \rightarrow \infty} \|\theta_J - \theta\| = 0$.

Theorem 4.1 :

If Assumptions 1-5 are satisfied and $J \rightarrow \infty$, then $\|\hat{\theta} - \theta_0\| \xrightarrow{p} 0$.